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TECHNICAL MEMORANDUM

(TM Series)

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Flight Specific Computer

Program Description

Alarm Clock

(ALACK)

Milestone 11

28 March 1963

Ву

D. J. Persico

Approved

B. G. Ciaccia

SYSTEM

DEVELOPMENT

CORPORATION

2500 COLORADO AVE.

SANTA MONICA

CALIFORNIA



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FUNCTION INDENTIFICATION

- A. Title: Alarm Clock (ALACK) Ident. K39, Mod AA.
- B. Programmed: D. Horton, 6594th Aerospace Test Wing, Sunnyvale
- C. Documented: D. J. Persico, System Development Corporation, March 28 1963.

PURPOSE

ALACK computes the positions of a satellite at specified time increments after acquisition by any of the stations, 1 (COOK), 5 (HULA), and 6 (BOSS).

USAGE

A. The function card format is:

*ALACK A B C

where: A is the vehicle number in decimal

B is the integral start revolution number in decimal

C is the integral stop revolution number in decimal.

B. Input Parameters

The orbit utilized is that which is defined by the parameters on the currently mounted reset tape. In addition, the Acquisition Table generated by a previous operation of the ACQTABLE function must be on the reset tape.

C. Output

The output is all printed on-line. The following output is obtained for each revolution between the input revolution parameters B and C, inclusive. The system times, beginning with the rise time of the first of the three stations (COOK, HULA, and BOSS) to acquire vehicle number A, preceding in 60 second intervals, and terminating with the system time of the last of the three stations to see vehicle number A, are listed chronologically. Parallel with this is a second list giving the latitude of the satellite for the corresponding system time in the first list. Next is a column giving the revolution number to the nearest tenth of vehicle number A for the corresponding

system time in the first column. Next are printed two more columns giving the latitude and longitude of the satellite at a system time equal to the system time in the first list, plus a constant delta time (A t). Finally, there are two more columns giving the latitude and longitude of the satellite at a system time equal to the system time in the first column, plus another constant delta time (A t). Interspersed among these outputs are the appropriately labelled rise and fade system times of any of the three stations which acquire vehicle number A on the current revolution. See Appendix B for sample ALACK output.

D. Method

For the 2300 flight series #50, certain vehicle equipment are controlled by a timer mechanism which is activated by real-time commands (RTC's) transmitted during a station pass. The geographical area over which the equipment will be operated is a function of the time at which the RTC was sent. The position of the satellite is projected forward for two different time intervals: from the time the first of the three stations acquires it and for every 60 seconds thereafter to the time the last of the three stations loses contact. The two revolution numbers on the function card delimit the procedure.

File 2 of the currently mounted reset tape is read into core. For each revolution between the input revolution parameters B and C, inclusive, ALACK searches the Acquisition Table for the stations COOK, HULA, and BOSS. If none of these stations have an entry in the table for the current revolution, this implies that there were no look requirements for any of the stations on the current revolution. In this case, ALACK prints out the comment "NO STATION ACQUISITION". The revolution number counter is incremented by one and, if it does not exceed the input stop revolution parameter C, a search is again made of the Acquisition Table.

If some K of the stations acquire the satellite on some revolution not exceeding the input stop revolution, $1 \le K \le 3$, the rise times and set times are computed from data in the Acquisition Table by the formulae:

rise time ≡ mid-pass time - [duration /2]

set time ≡ mid-pass time + [duration /2]

These 2K times are then sorted in chronological order

$$A : t_1 \le t_2 \le \cdots \le t_{2K}$$

where: t₁ is the rise time of the first station acquiring the satellite

 \mathbf{t}_{2K} is the set time of the last station to see the satellite.

Let m be a positive integer such that:

$$t_1 + 60 (m-1) \le t_{2K} < t_1 + 60m.$$

Then for each time:

$$B : t_1 + 60j, j=0, 1, 2, ---, m-1$$

ALACK computes and prints on-line the following quantities:

- a) latitude of the satellite and corresponding system time
- b) latitude and longitude of the satellite at time $t_1 + 60j + \Delta_1 t$, or at time $t_1 + 60j + \Delta_2 t$ depending on the direction of satellite motion
- c) latitude and longitude of the satellite at time $t_1 + 60j + \Delta_1 t + \Delta_3 t$, or at time $t_1 + 60j + \Delta_2 t + \Delta_3 t$ depending on which time was used in b).

These three time increments, Δ_1 t, Δ_2 t, and Δ_3 t, are entered into the program by octal overloads. The time values A and B are sorted chronologically. Corresponding to the times A there is printed the station name, event (rise or fade), system time, and satellite latitude. In case for some p, q

$$t_1 + 60p = t_q$$

the second type of printout predominates. This completes the processing for the current revolution. The revolution number counter is incremented by one and the processing repeated.

The direction of satellite motion referred to in b) is determined as follows. Each of the times in the set B which are not in the set A is entered into the reference pool cell TAU and the subroutine TTE executed. TTE computes the azimuth of the satellite's velocity vector and stores this value in the reference pool cell AZM. If $90^{\circ} \le \text{value of AZM in degrees} \le 270^{\circ}$,

then the satellite is travelling North to South. If any other inequality obtains, the satellite is travelling South to North.

The latitudes and longitudes referred to in a), b), and c) are determined as follows. The time at which the position is desired is entered into the reference pool cell TAU and the subroutine TTE executed. TTE computes the right ascension and desired latitude of the satellite and stores these values in the reference pool cells RA and LAT respectively. The right ascension (RA) is then converted to satellite longitude by the operation of the RALONG subroutine.

RESTRICTIONS

- A. The function ACQTABLE must have been executed prior to ALACK operation.
- B. ALACK computes satellite position for station number 1 (COOK), station number 5 (HULA), and station number 6 (BOSS), only.
- C. The contents of index registers 1, 2, 4, and 6 are destroyed.
- D. ALACK uses subroutines RESET, OUTERR, SUBERR, SETUP, OUTPUT, RALONG, TTE, and MACGUT.
- E. Error halts will occur if errors are encountered in subroutines SETUP, TTE, and MACGUT. Prior to program halt, the subroutine SUBERR is executed and an on-line console scoop will be printed on the CDC 1612 printer. In a like manner, an error encountered in the

output subroutine will result in the execution of the OUTERR subroutine and a program halt.

F. Reference pool items AZM, CLOCK, LAT, REV, RA, and TAU are used by ALACK. Additional reference pool items used or set by ALACK system subroutines are defined in the documents listed in the REFERENCE * section.

STORAGE REQUIREMENTS

1

1

A. Space Allocation

Program	17610	cells
Constants	2710	cells
Temporary Storage	51 ₁₀	cells
TOTAL	25410	cells

In addition, 2 cells of COMMON are used as temporary storage.

B. Program Constants

TAG	VALUE	FORMAT	DESCRIPTION
*Al	Classified	Floating Point	Classified
*A2	Classified	Floating Point	Classified
*A 3	Classified	Floating Point	Classified
СК		BCD	A three word buffer containing the BCD names COOK, HULA, BOSS
N		BCD	The BCD char. N
S		BCD	The BCD char. S
E		BCD	The BCD char. E
W		BCD	The BCD char. W
RADDEG	57.2957795131	Floating Point	Conversion factor for radians to degrees.
FXFL	201414000000000000	OCT	Conversion factor for fixed pt. to floating pt.

^{*} These values are obtained from the 6594th Aerospace Test Wing, Sunnyvale.

DESCRIPTION

FORMAT

TAG

VALUE

	F 60	60	Floating Point	Time increment
	MZERO	- 0	OCT	Used for negating
	PI/2	π/2	Floating Point	90 degrees
	PI	π	Floating Point	180 degrees
	rise		BCD	BCD word RISE
	FADE		BCD	BCD word FADE
	NOACQ		BCD	BCD statement
				NO STATION
				ACQUISITION
				(3 words)
	HEAD		BCD	6 word BCD heading
C.	Temporar	y Storage		
	TAG	LENGTH	DESCRIPTION	
	COM	3	Contains the event t	time, station name, and
	STAREV	1	Start revolution num	iber
	STOREV	1	Stop revolution numb	per
	revstn	1	Revolution number co	ounter
	STASTN	1	Station number	
	FINFLG	1	Indicates end of acq	uisition table
	STAFLG	1	Indicates a relevant a relevant revolution	station has been found on on
	COOKFLG	3	Stations which acqui	re on this revolution
	COOKRISE	3	Rise times	
	COOKSET	3	Set times	·
	CURRENT	1	Time counter	
	EARLY	6	Rise and set times s	orted chronologically
	DELTAL	2	Two time increments	
	BCD1	6	Station names corres buffer EARLY	ponding to times in the

TAG `	LENGTH	DESCRIPTION
BCD3	6	Words "RISE" or "FADE" corresponding to the event in the buffer EARLY
ITD	1	"N" or "S" depending on latitude at time CURRENT
LATO	1	Latitude
STMO	1	System time
LD1	2	"N" or "S" depending on latitude at time CURRENT plus two increments
LONGO1	2	Longitude at time CURRENT plus two increments
LG1	2	"E" or "W" depending on longitudes in buffer LONGOL
CL1	2	Latitudes at time CURRENT plus two increments
TARGET	1	Always contains zero
COMMON+1	1	Duration and mid-time
COMMON+2	1	[Duration /2]

VALIDATION TESTS

*

In Appendix B are three test cases of ALACK. The relevant Acquisition Table is shown on page 12. On page 13 is Test Case 1. The function card used is

*ALACK 2314 1 6

On revolution number 1, only COOK acquires vehicle number 2314 of the three stations COOK, HULA, and BOSS. On revolutions 2 through 5, none of the three stations acquire the satellite. On revolution number 6, only BOSS acquires the satellite. The rise and fade times listed can be readily verified.

On page 15 is Test Case 2. The function card used is *ALACK 2314 1 7

The output through revolution number 6 is identical with that of Test Case 1. On revolution number 7, only BOSS acquires vehicle number 2314.

On page 18 is Test Case 3. The function card used is *ALACK 2314 1 8

The output is identical with that of Test Case 2 through revolution number 7. On revolution number 8, only COOK acquires the vehicle.

TIMING

No general timing formula can be explicitly stated. The running time is a function of:

- 1) the difference between the stop and start revolution numbers on the function card
- 2) the number of stations acquiring the vehicle on a revolution
- 3) length of time the acquiring stations see the vehicle.

In Test Case 1 there were only two stations acquiring the vehicle across 6 revolutions. The satellite was in sight a total of 1032 seconds. This case took 9.102 seconds to execute. Test Case 2 ran forll.737 seconds. The difference in these two times is 2.635 seconds. Since the calculations are precisely the same for the first six revolutions, the extra time is that which revolution seven required. For this revolution, the total acquisition time is 628 seconds. Finally, revolution eight of Test Case 3 required 2.998 seconds to execute since all of Test Case 3 required 14.735 seconds. The total acquisition time on revolution eight is 668 seconds.

REFERENCES

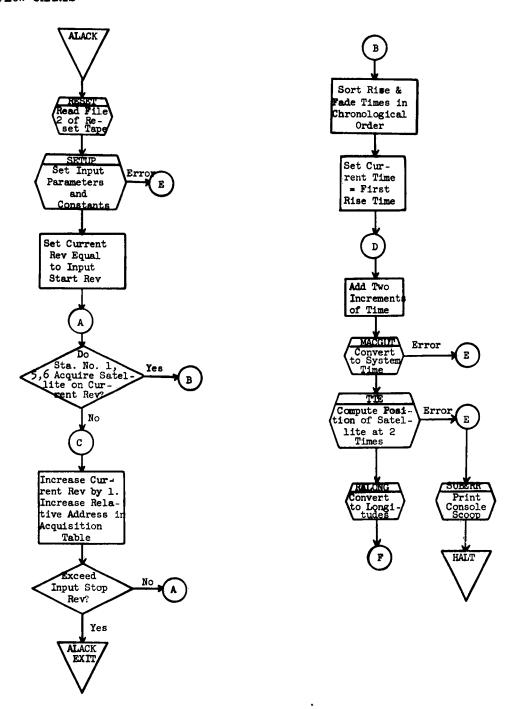
- TM-714/004/00, Milestone 11, Convert Machine Time to Universal Time and System Time (MACGUT), System Development Corporation, 18 May 1962.
- TM-714/019/00A, Milestone 11, Initialize Station and Earth Constants (SETUP), System Development Corporation, 2 January 1963.
- TM-714/030/00, Milestone 11, Generate, Update, and Read the Reset Tape (RESET), System Development Corporation, 4 December 1962.
- TM-714/021/00, Milestone 11, Convert Right Ascension to Longitude
 (RALONG), System Development Corporation, 17 September 1962.

1

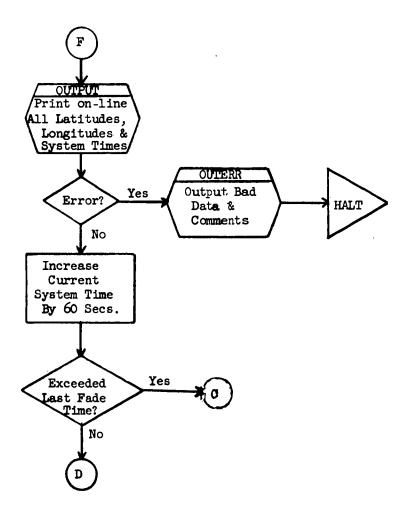
- TM-705/033/00, SCF Computer Program Systems Manual, Generalized Output Routine (OUTPUT), System Development Corporation, 16 January 1963.
- TM-715/032/00, Milestone 11, Generalized Output Error Routine (OUTERR), System Development Corporation, 7 December 1962.
- LMSD-447578, page 55.05.53, Systems Manual Subroutine Description for TTE, Lockheed Missile and Space Company, 20 February 1962.

APPENDIX A

FLOW CHARTS



1



APPENDIX B

			ACQUISITION		
		VEHICL	E 2314 R	UN NO. TESTCAS	E
		-	MIN, DUR,	120	
			JUNE 1,1	963	
HEV	ST	ATION	MID TIME	DURATION	MAX ELEV
1.3	4	KODI	1 42 20		73.07
1,4	20	HUNTS	1 47 40		10,37
1.4	1	COOK	1 48 34	356	3,21
2,3	4	KODI	3 17 23	610	15.68
2.4	20	HUNTS	3 23 21	686	38,11
0,1	6	BOSS	9 15 25	677	31,90
7.1	6	BOSS	10 51 2	629	16,84
8.1	1	COOK	12 22 44	669	28,94
9.1	20	HUNTS	13 57 43	233	1,25
9.1	1	COOK	13 58 17		13,36
y . 2	4	KOD1	14 3 32		14,61
10.1	20	HUNTS	15 32 22		70.41
10.2	4	KODI	15 38 33		77,90
11.1	20	HUNTS	17 8 18		5,34
11,2	4	KODI	17 14 46		13,55
12.2	4	KODI	18 52 14		1.59
12.3	6	8055	19 7 3		6,09
13.4	6	HOSS	20 43 13		85,22
14.3	4	KODI	22 9 14		.71
14.4	6	MOSS	22 18 0		5,94
14.4	1	COOK	22 18 33		.57
15.3	4	KODI	23 46 53		10.69
15.4	1	COOK	23 54 47	703	59,02
- •			JUNE 2,1		
REV	\$1	ATION	MIU TIME		MAX ELEV
16.3	4	KODI	1 23 17		57.59
10.4	20	HUNTS	1 20 33		7.16
10,4	1	COOK	1 29 42	456	5,93
17.3	4	KODI	2 50 28		19,19
17,4	20	HUNTS	3 4 23	697	54,98

Test Case 1

VEH	2314	4FA	1.0						
COOK	RISE		6336.0	45.8N					
			6396.0	42.1N	1,4	34.6N	143.94	30,9N	143.4W
			6456.0	38.4N	1,4	30.9N	143.4W	27.1N	143,0w
			6516.0	34.6N	1,4	27.1N	143.0#	23,4N	142.6W
			6576.0	30.9N	1,4	23.4N	142.6#	19.0N	142.2W
			6636.0	27.1N	1,4	19.6N	142.2*	15.0N	141.84
∟ 0∪⊀	FAGE		6692,0	23.6N					

VEH 2314 REV 2.0

1

NO STATION ACQUISITION

VEH 2314 ALV 3.0

NO STATION ACQUISITION

Test Case 1 (cont.)

VEH 2314 REV 4,0

NO STATION ACQUISITION

VEH 2314 REV >+0

NO STATION ACQUISITION

AF4	2314	# E V	0.0						
r0\$\$	RISE		32987.0	21.2N					
			33047.0	24.9N	6,1	39.9N	63.6W	43.04	62,8W
			33107.0	28,7N	6,1	43.6N	62.8W	47.4N	62.0w
			33167.0	32,4N	6,1	47.4N	62.04	51.1N	61.0W
			33227.0	36.2N	6,1	51.1N	61.04	54,8N	59,74
			33287.0	39.9N	6,1	54.8N	59.71	58,5N	58,2¥
			33347.0	43.6N	6,2	58.5N	56.24	62.1N	56.2W
			33407.0	47,4N	6,2	62.1N	56 .2×	65,7N	53.7k
			33467.0	51.1N	6,2	65.7N	53.7H	69.2N	50.3W
			53527.0	54.5N	6.2	69.28	50.3×	72.6N	45.4W
			33567.0	58.5N	6,2	72.6N	45,44	75.9N	36,2W
			33647.0	62.1N	6,2	75.9N	38,24	78,6N	27.1W
,055	FADE		33663.0	63,1N					

Test Case 2

YEH	2314	9ĕV	3.0						
COOK	RISE		6336.0	45,8N					
			6396.0	42,1N	1,4	34.6N	143,94	30.74	143,44
			6456.0	38,4h	1,4	30.9N	143,44	27,ĮN	143.0W
			6516.0	34,6N	1,4	27.14	143.0#	23,4N	142,6W
			6576.0	30,9N	1,4	23.4N	142.64	19,6N	142.28
			6636.0	47.1N	1.4	19 + 6N	142.24	15.6N	141.8#
COUK	FADE		6692.0	43.6N					

Ve4 2314 4EV 2,0

NO STATION ACGUISITION

Vet 2314 REV 3.0

NO SIATION ACQUISITION

Test Case 2 (cont.)

VEH 2314 REV 4.0

NO STATION ACQUISITION

VEH 2314 REV 5.0

NO STATION ACQUISITION

VEH 2314 REV ... BOSS RISE 32987.0 21.2N 6,1 39.9N 63,4H 33047.0 24.9N 43,6N 62,8H 33107,0 28,7N 43.6N 47,4N 62.0H 62,8¥ 33167.0 32.4N 47.4N 62.0% 51.1N 61.0W 61.04 54,8N 59.7W 33227.0 36.2N 51 • 1N 54.8N 59,78 58,5N 58.2W 33287.0 39.9N 6.1 33347.0 43.6N 6,2 58.5N 58.2W 62,1N 56,2W 45,7N 53,7W 33407.0 \$7.4N 6,2 62,1N 56,2W 33467.0 51.1N 65.7N 53.7¥ 69.2N 50.3H 6,2 72.9N 45.4H 33527.0 54.8N 6.2 69.2N 50.3W 6.2 72.6N 45.4W 75.9N 38.2H 33587.0 58.5N 6,2 75,9N 38,2W 78,6N 27.1H 33647.0 92.1N 33663,0 63,1N BOSS FADE

Test Case 2 (cont.)

VE-4	2314	REV	7,0						
6055	HISE		38748.0	26.0N					
			38508.0	29.7N	7,1	44.7N	86,44	48,4N	85.5W
			38868.0	33,5N	7,1	48.4N	85,5¥	52,1N	84.5W
			38925,0	\$7.2N	7.1	52.1N	84,5%	55,8N	83,2W
			38988,0	41.0N	7.2	55,84	83.2 m	59,5N	81.5W
			39048.0	44.7N	7,2	59.5N	81,54	63,1N	79.4W
			39108.0	48.4N	7.2	63.1N	79.44	66.7N	76.7¥
			39168.0	52.1N	7.2	66.7N	76.7₽	70.2N	72.9×
			39228.0	>5.AN	7,2	70.2N	72,9¥	73.6N	67.5¥
			39288.0	59.54	7,2	73.6N	67.54	76.7N	59.44
			39348,0	63.1N	7.2	76.7N	59.44	79,5N	46.84
60SS	FADE		39376.0	64.8N					

Test Case 3

AEH	2314	REV	1.0						
COOK	M [SE		6336.0	45.8N					
			6396.0	42.1N	1.4	34.6N	143.94	30.9N	143.4W
			6456.0	48,4N	1,4	38.9N	145.48	27.1N	143.0W
			6516.0	54.6N	1,4	27.1N	145.0H	23,4N	142.68
			6576.0	30.9N	1.4	23.4N	142.68	19.5N	142.24
			636.0	47.1N	1.4	19.6N	142.24	15.6N	141.84
COOK	FADE		6692.0	23.6N					

Test Case 3 (cont.)

VEH 2314 PEV 2.0

NO STATION ACQUISITION

Ved 2314 REV 3.0

NO STATION ACQUISITION

Vtm 2314 PEV 4,8

NO STATION ACQUISITION

Test Case 3 (cont.)

VEH 2314 REV 5.0

NO STATION ACQUISITION

VEH	2314	REV	•.0						
8088	RISE		32987.0	21.2 N					
			33047,0	34.9N	4,1	39.9N	43,6¥	48 ₄ 6N	62,8W
			33107,0	28.7N	4,1	43,6N	62,84	47 ₁ 4N	42.0H
			33167,0	32.4N	4.1	47,4N	62.0W	91,1N	61.0¥
			33227.0	36.2N	4,1	51.1N	61.04	54,0N	59.7W
			33287.0	39.9N	6,1	54 <u>.</u> 8N	59,7¥	Ş0,ŞN	58.2W
			33347.0	43,6N	4.2	58 ₁ 5N	50,24	62.1 N	56,2W
			33407.0	57.4N	6,2	68.1N	96,24	65,7 1€	58,7¥
			33467.0	\$1.1N	6,2	65.7N	53,79	60'SN	50,3W
			33527.0	54.8N	6,2	47:2N	50,3V	72,6N	45,4H
			33507.0	58,5N	4,2	78±6N	45,41	75.7N	36,2W
			33647.0	≜2,1 N	6,2	75 ₂ 9N	38.24	78, Q N	27.1W
9088	FARE		33443.0	43.4N					

VEH 2314 REV 7.0

BOSS RISE 38748,0 20.0N

38808.0 20.7N 7.1 44.7N 66.4W 48.4M 85.8W

38868.0 33.5N 7.1 48.4N 85.9W 52.4N 84.8W

38928.0 37.2N 7.1 52.1N 84.5W 55.0N 83.2W

38988.0 41.0N 7.2 55.8N 83.2W 99.5N 81.8W

30048.8 44.7N 7.2 59.5N 81.5W 63.4N 79.4W

COOK PAGE

Test Case 3 (cont.)

	39108.0	48,4N	7,2	63.1N	77.44	66.7N	76.7W
	39168,0	52,1N	7,2	66.7N	76,74	70,2N	72,9W
	39226,0	55.8N	7.2	70.2N	72.9¥	73,6N	67.54
	39288.0	59,5N	7.2	73.6N	67.5¥	76.7N	59.4H
	39348.0	63.1H	7.2	76.7N	59.44	79,5N	46,84
SOSS FARE	39376.0	64.AN					

VEH 2314 REV 8,0 COOK RISE 44230.0 13.3N 44290.0 17.1N 8,1 32,1N 112,4W 35,8N 111,9W 44350,0 20,8N 35.8N 111.9W 39,6N 111,3W 44410.0 24.6N 39.6N 111.3W 43,3N 110,5W 44470.0 28.3N 43.3N 110.5W 47.0N 109.7W 44530.0 32.1N 47.0N 109.7W 50.7N 108.7W 44590.0 35.8N 59.7N 108,7W 54.4N 107.5W 44650.0 39.6N 54.4N 107.5W 58,1N 106,0W 44710.0 43.3N 58.1N 106.0H 61.8N 104.1W 44770.0 47.0N 61.8N 104.1W 65,4N 101,6W 65.4N 101.6W 44830.0 50.7N 68,9N 98.3H 44890.0 54.4N 68.9N 98.3H 72.3N. 93.6W

44898.0 54.9N

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External Distribution List

Space Systems Division (Contracting Agency) Major C. R. Bond (SSOCD)

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S. M. Stanley

PIR-E3 (LFE)

D. F. Criley

K. B. Williams

PIR-E8 (Mellonics)

F. Druding

PIR-E5 (Aerospace)

F. M. Adair

R. O. Brandsberg

L. H. Garcia

G. J. Hansen

C. S. Hoff

L. J. Kreisberg

T. R. Parkin

E. E. Retzlaff

H. M. Reynolds

D. Saadeh

R. G. Stephenson

V. White

PIR-E4 (GE - Sunnyvale)

J. Farrentine

N. Kirby

PIR-E4 (GE - Santa Clara)

D. Alexander

PIR-E4 (GE = Box 8555)

J. S. Brainard

R. J. Katucki

J. D. Selby

PIR-E4 (GE - 3198 Chestnut)

J. F. Butler

H. D. Gilman

(5)

PIR-E4 (GE - Bethesda)

W. L. Massey

PIR-E4 (GE - Box 8661)

J. D. Rogers

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System Development Corporation,
Santa Monica, California
FLIGHT SPECIFIC COMPUTER PROGRAM
DESCRIPTION ALARM CLOCK (ALACK)
MILESTONE 11.
Scientific rept., TM(L)-742/006/00,
by D. J. Persico, 28 March 1963, 21p.
(Contract AF 19(628)-1648, Space Systems
Division Program, for Space Systems
Division, AFSC)

Unclassified report

DESCRIPTORS: Programming (Computers). Satellite Networks.

Reports that ALACK (Alarm Clock) computes the positions of a

1

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satellite at specified time increments after acquisition by any of the stations, 1 (COOK), 5 (HULA), and 6 (BOSS).

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